
A Theoretical Characterization of Linear SVM-Based Feature Selection: Supplement

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A. Proof of Lemma 1

Proof of Lemma 1. As we outline below, the optimization problems (L.1) and (L.2) can be expressed in terms of an objective function $F(\mathbf{w}, b)$ that is minimized over a compact convex set $C \subset \mathbf{R}^N \times \mathbf{R}$ where the objective function F is continuous and can be written in the form

$$F(\mathbf{w}, b) = h(\mathbf{w}) + g(\mathbf{w}, b) \quad (1)$$

for some convex function g and where h is a strictly convex function. In fact, in all the cases considered here we have $h(\mathbf{w}) := |\mathbf{w}|^2$.

First we show that the respective optimization problems can be restricted to only considering (\mathbf{w}, b) in a compact convex set C . Suppose (\mathbf{X}, Y) is separable. For the sample limit hard-margin problem (L.1) we construct C as follows. Let \mathcal{W} denote the collection of “admissible” (\mathbf{w}, b) satisfying the constraint (8). Let $(\mathbf{w}^*, b^*) \in \mathcal{W}$, $r_* = |\mathbf{w}^*|$, and define $C := \{(\mathbf{w}, b) \in \mathcal{W} \mid |\mathbf{w}| \leq r_*\}$. By hypothesis there is some R such that $|\mathbf{X}| \leq R$ almost surely. If $(\mathbf{w}, b) \in C$ then $|\mathbf{w}| \leq r_*$ and it follows that $|b| \leq 1 + r_*R$ showing that C is bounded and hence compact. For the hard-margin case we have $g(\mathbf{w}, b) = 0$. Then $F(\mathbf{w}, b) = |\mathbf{w}|^2 > F(\mathbf{w}^*, b^*) = r_*^2$ for $(\mathbf{w}, b) \in \mathcal{W} \setminus C$ and so $\min_{(\mathbf{w}, b) \in \mathcal{W}} F(\mathbf{w}, b) = \min_{(\mathbf{w}, b) \in C} F(\mathbf{w}, b)$.

In the sample limit soft-margin (unconstrained form) case (L.3), we have $g(\mathbf{w}, b) = CE([1 - Y(\mathbf{w} \cdot \mathbf{X} + b)]_+^p)$. Fix (\mathbf{w}^*, b^*) and let $r_* := \sqrt{F(\mathbf{w}^*, b^*)}$. If $|\mathbf{w}| > r_*$, then $F(\mathbf{w}, b) \geq h(\mathbf{w}) > r_*^2 = F(\mathbf{w}^*, b^*)$. Since $\min_{|\mathbf{w}| \leq r_*} g(\mathbf{w}, b) \rightarrow \infty$ as $|b| \rightarrow \infty$, there is some $\gamma > 0$ such that $g(\mathbf{w}, b) \geq r_*$ for $|b| > \gamma$ and $|\mathbf{w}| \leq r_*$. Hence, letting $C := \{(\mathbf{w}, b) \mid |\mathbf{w}| \leq r_* \text{ and } |b| \leq \gamma\}$ we have $\min_{(\mathbf{w}, b) \in \mathbf{R}^N \times \mathbf{R}} F(\mathbf{w}, b) = \min_{(\mathbf{w}, b) \in C} F(\mathbf{w}, b)$.

Since F is continuous and C is compact then there must be some global minimizer $(\boldsymbol{\omega}, \beta) \in C$. Suppose $F(\boldsymbol{\omega}', \beta') = F(\boldsymbol{\omega}, \beta)$ then $(\tilde{\boldsymbol{\omega}}, \tilde{\beta}) := ((\boldsymbol{\omega} + \boldsymbol{\omega}')/2, \beta + \beta')/2 \in C$ since C is convex. If $\boldsymbol{\omega}' \neq \boldsymbol{\omega}$ then we have (since g is convex and h is strictly convex) $g(\tilde{\boldsymbol{\omega}}, \tilde{\beta}) \leq (g(\boldsymbol{\omega}, \beta) + g(\boldsymbol{\omega}', \beta'))/2$ and $h(\tilde{\boldsymbol{\omega}}) < (h(\boldsymbol{\omega}) + h(\boldsymbol{\omega}'))/2$ and thus $F(\tilde{\boldsymbol{\omega}}, \tilde{\beta}) < F(\boldsymbol{\omega}, \beta)$ contradicting the fact that $F(\boldsymbol{\omega}, \beta) = \min_{(\mathbf{w}, b) \in C} F(\mathbf{w}, b)$. Hence, $\boldsymbol{\omega}' = \boldsymbol{\omega}$.

The m -sample optimization problems (F.1) and (F.3) can be expressed in terms of minimizing an objective function $F_m(\mathbf{w}, b) = h(\mathbf{w}) + g_m(\mathbf{w}, b)$ of the form (1) over a compact convex set C_m . In the hard-margin case $g_m = 0$ and $C = \bigcap_m C_m$ almost surely. In the soft-margin case we can choose $C_m = C$ and

$$g_m(\mathbf{w}, b) = \frac{C}{m} \sum_{k=1}^m [1 - y_k(\mathbf{w} \cdot \mathbf{x}_k - b)]_+^p.$$

In both cases we have with probability 1 that $g_m \rightarrow g$ uniformly on compact sets in $\mathbf{R}^N \times \mathbf{R}$ as $m \rightarrow \infty$ and that $C_m \supset C$ and $C = \bigcap_m C_m$. Let $(\mathbf{w}_m, b_m) \in C_m$ be a global minimizer for F_m . Suppose (\mathbf{w}^*, b^*) is a limit point of the sequence (\mathbf{w}_m, b_m) (that is, some subsequence (\mathbf{w}_m, b_m) converges to (\mathbf{w}^*, b^*)) and that $\mathbf{w}^* \neq \boldsymbol{\omega}$. Then

$$\limsup_{m \rightarrow \infty} F_m(\mathbf{w}_m, b_m) \geq F(\mathbf{w}^*, b^*) > F(\boldsymbol{\omega}, \beta). \quad (2)$$

On the other hand, we have

$$\limsup_{m \rightarrow \infty} F_m(\mathbf{w}_m, b_m) \leq \limsup_{m \rightarrow \infty} F_m(\boldsymbol{\omega}, \beta) = F(\boldsymbol{\omega}, \beta)$$

which contradicts (2). Hence any limit point (\mathbf{w}^*, b^*) of the sequence (\mathbf{w}_m, b_m) must have $\mathbf{w}^* = \boldsymbol{\omega}$. Since the (b_m) is a bounded sequence any subsequence of (b_m) must contain a convergent subsequence showing that

ω is the only limit possible limit point of the sequence (\mathbf{w}_m) . Since (\mathbf{w}_m) is a bounded sequence in \mathbf{R}^N this implies that $\mathbf{w}_m \rightarrow \omega$ almost surely.

Finally, we address the uniqueness of β . In the hard margin case, there must be some (\mathbf{x}, y) in the support of (\mathbf{X}, Y) such that $y(\omega \cdot \mathbf{x} + b) = 1$ otherwise (ω, β) is an interior point of the constraint set and cannot be a minimizer. For the soft-margin case with $p > 1$ it is more direct to consider the equivalent constrained problem (L.2). In this case the objective function $\mathcal{F}_s(\mathbf{w}, b, \xi) = h(\mathbf{w}) + q(\xi)$ where q is a strictly convex function of $\xi = \xi(\mathbf{X}, Y)$ and it follows that (\mathbf{w}, ξ) are uniquely defined for any minimizer (\mathbf{w}, b, ξ) almost surely. Then, as in the hard-margin case, there must be some (\mathbf{x}, y) in the support of (\mathbf{X}, Y) for which we have equality in the constraints and thus b is uniquely determined. \square